

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	5	382/103,106,151,152,153,186,313,314,315,188,189,187;348/169,113,116,170,171,175;356/3;235/411. ccls. and (video near3 camera\$1 or camera or captur\$3 near3 device\$1 or image near3 pickup or CCD or sensor\$1)same robot near3 arm and (controller near3(base or arm))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2004/12/13 13:31
L2	7	controller\$1 near3 within near3 robot\$4 near3 (arm\$1 or extremity\$4 or base)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2004/12/13 13:32
L3	21	((target\$2 or mark\$2)near5(surface or substrate or paper near3 sheet or board or layer)same (camera\$1 or sensor\$2 or captur\$4 near3 device\$1 or image\$3 near3 pickup)) and detec\$5 near5 (target\$2 or mark\$2)same (frame-by-frame or frame near3 frame)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2004/12/13 13:33
L4	2	(382/103,106,151,152,153,186,313,314,315,188,189,187;348/169,113,116,170,171,175;356/3;235/411. ccls. and (video adj1 camera or camera)near3 robot adj1 arm) and (track\$3 or trac\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2004/12/13 13:34